Lecture 1: introduction to bipartite matching

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Outline

- Graph theory basics
- Bipartite matching problem
- Greedy algorithm for maximum bipartite matching

Introduction

Königsberg



• Question: Starting from a certain region, is it possible to traverse all bridges exactly once and come back to the initial location?

Introduction

• Abstraction of Königsberg's map



• The second figure is referred to as a graph.

Elements of graphs

• A graph G consists of its vertex set V and an edge set E.



- We say that two vertices *u* and *v* are **adjacent** if there is an edge *uv* ∈ *E* between them.
- Moreover, we call any vertex adjacent to *u* a **neighbor** of *u*.
- We say that a vertex *u* is **incident** to an edge *e* if *u* is one of the endpoints of *e*.
- The **degree** of a vertex is the number of its neighbors which equals the number of incident edges to it.

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Complete graphs

Bipartite graphs

Complete bipartite graphs

Paths

A walk is a sequence of vertices v₀, v₁,..., v_k where any two consecutive vertices are adjacent, i.e., v_{i-1}v_i ∈ E for any i ∈ {1,...,k}.



Figure: a walk(left) and a path(right)

- An *uv*-walk is a walk whose initial vertex is *u* and the final vertex is *v*.
- A **path** is a walk where no vertex is visited more than once.
- An *uv*-**path** is a path that starts with *u* and ends with *v*.

Cycles

- A closed walk is a walk v_0, v_1, \ldots, v_k that ends with the initial vertex, i.e., $v_0 = v_k$.
- A cycle is a closed walk v_0, \ldots, v_k that repeats no vertex except for $v_0 = v_k$.



Figure: a closed walk(left) and a cycle(right)

Length and parity

- The length of a walk is the number of edges that it takes.
- A **shortest path** between two vertices *u* and *v* is an *uv*-path with the minimum length.
- A cycle of an odd length is referred to as an **odd** cycle.
- A cycle of an even length is called an **even** cycle.

Subgraphs

- Given a graph G = (V, E), a **subgraph** of G is given by G' = (V', E') such that $V' \subseteq V$, $E' \subseteq E$, and E' is defined over V'.
- This means that the endpoints of the edges in E' are fully contained in V'.



Figure: a graph, a subgraph, and an induced subgraph

- An induced subgraph H of G is a subgraph of G defined with a vertex subset $U \subseteq V$ so that uv is an edge in H if and only if $u, v \in U$.
- Here, we say that *H* is a **subgraph induced by** *U*.
- A clique is a subgraph that is a complete graph.

Equivalent characterization of bipartite graphs

Lemma

A closed walk of an odd length contains an odd cycle as a subgraph.

Proposition

A graph is bipartite if and only if it has no odd cycle as a subgraph.

Equivalent characterization of bipartite graphs

Bipartite matching

- Recall that a bipartite graph is a graph G = (V, E) where
 - the vertex set V is partitioned into two sets V_1 and V_2 ,
 - each edge $e \in E$ crosses the partition, i.e. e has one end in V_1 and the other end in V_2 .



- A matching is a set of edges without common vertices.
- A maximal matching is a matching that cannot be extended to a matching of a larger cardinality.
- In other word, a maximal matching is not properly contained in another matching.
- A maximum matching is a matching with the maximum number of edges.

Maximum bipartite matching problem

- The **maximum bipartite matching** problem is to find a matching that has the maximum number of edges.
- The maximum bipartite matching problem can model a wide range of applications in practice.
- As the name suggests, it provides a natural framework for couple matching scenarios.



Applications of bipartite matching

• US medical students are matched with residency programs by the National Resident Matching Program (NRMP) based on bipartite matching.



Applications of bipartite matching

- Online advertisement slot allocation is another exemplary application of bipartite matching.
- Online platforms run auctions to sell their advertisement slots to advertisers.



Applications of bipartite matching

- **Recommender systems**: A bipartite graph can represent user-item preference information.
- Economic matching markets: Bipartite networks can model how markets work between two disjoint parties of players, such as buyers and sellers. Online ad allocation is an example.
- Job-server scheduling: In a large data center, jobs to be processed arrive in real time, and the scheduler assigns them to multiple servers and processors based on their computing requirements.

- How do we compute a maximum matching in a bipartite graph?
- One natural approach is to **greedily** select and add edges without destroying the matching structure.

Algorithm 1 Greedy algorithm for bipartite matching

```
Enumerate the edges in E as e_1, \ldots, e_{|M|}
Initialize M = \emptyset.
for i = 1, \ldots, |E| do
If M \cup \{e_i\} is a matching, then update M as M = M \cup \{e_i\}.
end for
Return M
```

- Does the greedy algorithm find a maximum matching for a bipartite graph?
- Unfortunately, that is not always the case.



- Can we understand how small a matching returned by the greedy algorithm is compared to the size of a maximum matching?
- The following result shows that the greedy algorithm can achieve at least 50% of the maximum size.

Theorem

Let G = (V, E) be a bipartite graph, and let M be a maximal matching. Then

$$|M| \ge \frac{1}{2}$$
OPT

where OPT denotes the maximum size of a matching in G.

Since the greedy algorithm always finds a maximal matching, it is an (1/2)-approximation algorithm for maximum bipartite matching.