

Lecture 10: discrete and continuous submodular function maximization

Dabeen Lee

Industrial and Systems Engineering, KAIST

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Outline

- Submodular set function maximization
- Submodular function maximization subject to a matroid constraint
- Continuous DR-submodular maximization

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Submodular set function

- A function $f : 2^V \rightarrow \mathbb{R}$ over the subsets of finite ground set V is **submodular** if

$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B) \quad \forall A, B \subseteq V.$$

- Submodularity is equivalent to the **diminishing (marginal) returns** property.
- To be precise, $f : 2^V \rightarrow \mathbb{R}$ is submodular if and only if

$$\underbrace{f(A \cup \{v\}) - f(A)}_{\text{marginal return from adding } v \text{ to } A} \geq \underbrace{f(B \cup \{v\}) - f(B)}_{\text{marginal return from adding } v \text{ to } B} \quad \forall A \subseteq B, v \notin B$$

- A common analogy: at a buffet restaurant, you feel less happy with the second plate than with the first plate.

Examples of submodular set functions

The area covered by sensors

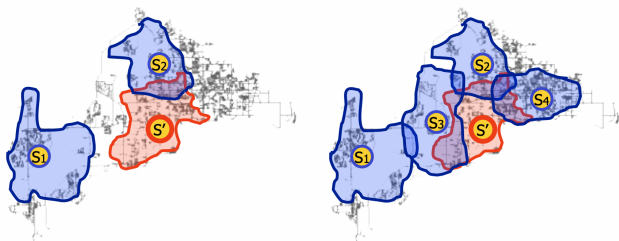


Figure: Adding sensor s' to $\{s_1, s_2\}$ (left) and $\{s_1, s_2, s_3, s_4\}$ (right)

- Let A_v be the area covered by a sensor v .
- Then f defined as

$$f(S) = \left| \bigcup_{v \in S} A_v \right|, \quad S \subseteq V$$

is submodular.

¹Taken from [Krause and Golovin, 2014]

Examples of submodular set functions

Joint stochastic utility

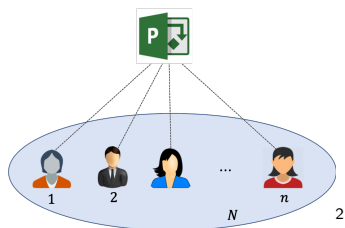


Figure: Employees with random performance

- n employees with random performance values X_1, \dots, X_n .
- Then

$$\mathbb{E} \left\{ \max_{v \in S} X_v \right\}, \mathbb{E} \left\{ \sqrt{\sum_{v \in S} X_v} \right\}, \mathbb{E} \left\{ \sqrt{\sum_{v \in S} X_v^2} \right\}$$

are all submodular functions over $S \subseteq V$.

²Taken from Milan Vojnovic's slides.

Submodular set function maximization

Submodular function maximization (SFM)

$$\begin{aligned} & \text{maximize} && f(S) \\ & \text{subject to} && S \in \mathcal{F} \subseteq 2^V \end{aligned}$$

where

- f is submodular and **monotone**, i.e., $f(A) \leq f(B)$ for any $A \subseteq B$,
- \mathcal{F} is the **constraint set**.

Constraint set examples:

- Cardinality constraint: $\mathcal{F} = \{S \subseteq V : |S| \leq k\}$.
- Knapsack constraint: $\mathcal{F} = \{S \subseteq V : \sum_{i \in S} c_i \leq B\}$.
- Matroid: $\mathcal{F} = \{S \subseteq V : S \text{ is an independent set of matroid } \mathcal{M}\}$.

Applications of SFM

Business operations

- Online freelancing platforms [Sekar et al., 2020].
- Team selection - sports teams, online gaming [Kleinberg and Raghu, 2015].
- Assortment selection in online shopping websites [Udwani, 2021].
- Influence maximization [Kempe et al., 2003].

Machine learning

- Feature and variable selection [Krause and Guestrin, 2005].
- Dictionary learning [Das and Kempe, 2011].
- Document summarization [Lin and Bilmes, 2010, 2011].
- Image summarization [Mirzasoleiman et al., 2018, Tschitschek et al., 2014].
- Active set selection in non-parametric learning [Mirzasoleiman et al., 2016].

NP-hardness of SFM

- [Cornuéjols et al., 1977]

SFM is **NP-hard** even with a monotone objective subject to a cardinality constraint.

- No polynomial time **exact** algorithm is known.
- If one exists, it would imply a polynomial time exact algorithm for traveling salesman problem (TSP).
- However, there exist polynomial time **constant approximation** algorithms.

Approximation algorithm

- We say that a solution $\bar{S} \in \mathcal{F}$ is α -approximate for some $\alpha \in [0, 1]$ if

$$f(\bar{S}) \geq \alpha \cdot \max_{S \in \mathcal{F}} f(S).$$

- An α -approximation algorithm would always find an α' -approximate solution for some $\alpha' \geq \alpha$ for every instance of SFM.
- In other words, the worst-case guarantee is always as good as α times the optimal value.
- A constant approximation algorithm is an α -approximation algorithm for some fixed $\alpha > 0$.

Greedy algorithm

- Let us explain a simple greedy algorithm by [Nemhauser et al., 1978] that guarantees an $(1 - 1/e)$ -approximate solution.
- The idea is that until we reach the size limit, we take an element that achieves the maximum marginal return value.

Algorithm 1 Greedy algorithm for submodular maximization

Initialize $S = \emptyset$

while $|S| < k$ **do**

 Take an element $v \in \arg \max \{f(S \cup \{v\}) - f(S) : v \in V \setminus S\}$

end while

Return S

Greedy algorithm

Theorem ([Nemhauser et al., 1978])

Let $\bar{S} \subseteq V$ be the outcome of Algorithm 1. Assume that $f(\emptyset) = 0$. Then

$$f(\bar{S}) \geq \left(1 - \frac{1}{e}\right) \max \{f(S) : |S| \leq k\}.$$

Greedy algorithm

Approximation algorithms for SFM

Monotone SFM

- [Nemhauser et al., 1978]

$(1 - 1/e)$ -approximation algorithm for a **cardinality constraint**, where $(1 - 1/e) \approx 0.63$. Moreover, the factor $(1 - 1/e)$ is tight.

- [Sviridenko, 2004]

$(1 - 1/e)$ -approximation algorithm for a **knapsack constraint**.

- [Calinescu et al., 2007, Vondrak, 2008]

$(1 - 1/e)$ -approximation algorithm for a **matroid constraint**.

- [Kulik et al., 2009]

$(1 - 1/e)$ -approximation algorithm for a **system of linear constraints**.

There are constant approximation algorithms for **non-monotone SFM**.

Approximation algorithm for a matroid constraint

Outline

- Obtain a continuous relaxation of (discrete) SFM.
- Solve the continuous relaxation.
- Round the (fractional) solution to obtain a (discrete) solution to SFM.

Approximation algorithm for a matroid constraint

Outline

- Obtain a continuous relaxation of (discrete) SFM.
→ **Multilinear extension** + **Polymatroid**
- Solve the continuous relaxation.
→ **Continuous greedy algorithm**
- Round the (fractional) solution to obtain a (discrete) solution to SFM.
→ **Pipage rounding**

Multilinear extension

Multilinear extension [Vondrak, 2008]

- A set function $f : 2^V \rightarrow \mathbb{R}$ can be turned into a function $f : \{0, 1\}^V \rightarrow \mathbb{R}$ over binary variables.
- Given $f : \{0, 1\}^V \rightarrow \mathbb{R}$,

$$F(x) = \sum_{S \subseteq V} f(S) \prod_{v \in S} x_v \prod_{v \notin S} (1 - x_v) \quad \text{for } x \in [0, 1]^V$$

is the multilinear extension of f .

- Note that

$$F(1_S) = f(S) \text{ for every } S \subseteq V.$$

- Moreover,

$$F(x) = \mathbb{E}_{S \sim x} [f(S)]$$

where $S \sim x$ means sampling S by selecting each v with probability x_v .

Polymatroid

Polymatroid [Edmonds, 1970]

- Matroid constraint set is given by

$$\mathcal{F} = \{S \subseteq V : S \text{ is an independent set of matroid } \mathcal{M}\}.$$

- What is the right continuous relaxation for \mathcal{F} ?
- For $S \subseteq V$, $\text{rank}(S)$ is defined by the max size of an independent set in S .
- Then the **polymatroid** of matroid \mathcal{M} is given by

$$P = \left\{ x \in [0, 1]^V : \sum_{v \in S} x_v \leq \text{rank}(S) \quad \forall S \subseteq V \right\}.$$

- Here, $P \cap \{0, 1\}^V = \mathcal{F}$.

Continuous relaxation

- Given the multilinear extension F and the polymatroid P ,

$$\begin{aligned} & \text{maximize} && F(x) \\ & \text{subject to} && x \in P \subseteq [0, 1]^V \end{aligned}$$

is a continuous relaxation of SFM, given by

$$\begin{aligned} & \text{maximize} && f(S) \\ & \text{subject to} && S \in \mathcal{F} \subseteq 2^V. \end{aligned}$$

- In particular,

$$\max_{x \in P} F(x) \geq \max_{S \in \mathcal{F}} f(S).$$

Continuous greedy algorithm

Algorithm 2 Continuous greedy algorithm [Calinescu et al., 2007, Vondrak, 2008]

Start with $x(0) = 0$.

Let $v(x) = \arg \max_{v \in P} \{\nabla F(x)^\top v\}$.

Set $dx/dt = v(x)$.

Output $x(1)$.

- We can discretize the algorithm.

Theorem ([Calinescu et al., 2007, Vondrak, 2008])

$x(1) \in P$ and

$$F(x(1)) \geq \left(1 - \frac{1}{e}\right) \max_{S \in \mathcal{F}} f(S)$$

Pipage rounding

Theorem ([Ageev and Sviridenko, 2004, Calinescu et al., 2007])

There is a randomized polynomial time algorithm that given any $x \in P$, returns $S \in \mathcal{F}$ with

$$\mathbb{E}[f(S)] \geq F(x).$$

Together with the previous theorem,

$$\mathbb{E}[f(S)] \geq F(x(1)) \geq \left(1 - \frac{1}{e}\right) \max_{S \in \mathcal{F}} f(S).$$

Extension to the continuous domain

Extension

- There were two continuous components in the algorithm.
 1. Multilinear extension
 2. Continuous greedy algorithm
- We extend the multilinear extension to **continuous submodular functions**.
- We adapt the continuous greedy algorithm to develop the **conditional gradient method**, which is a **first-order iterative algorithm**.

Properties of the multilinear extension

- Recall that the multilinear extension is given by

$$F(x) = \sum_{S \subseteq V} f(S) \prod_{v \in S} x_v \prod_{v \notin S} (1 - x_v).$$

- It satisfies the following **diminishing returns (DR) property**:

$$F(x + \delta e_i) - F(x) \geq F(y + \delta e_i) - F(y)$$

for any $\delta \geq 0$ and $x, y \in [0, 1]^V$ with $x \leq y$.

- The multilinear extension is neither convex nor concave.
- But it is **concave along any nonnegative direction (up-concave)** $v \geq 0$, i.e.,

$$g(t) = F(x + t \cdot v)$$

is concave with respect to t .

- The multilinear extension is **smooth**, i.e. there exists $\beta > 0$ such that

$$\|\nabla F(x) - \nabla F(y)\|_2 \leq \beta \|x - y\|_2.$$

- Based on these properties, we extend submodularity to continuous functions.**

Continuous DR-submodular function

- We say that a function $F : \mathbb{R}^d \rightarrow \mathbb{R}$ is (continuous) DR-submodular if it satisfies the diminishing returns (DR) property.
- For some domain C ,

$$F(x + \delta e_i) - F(x) \geq F(y + \delta e_i) - F(y)$$

for any $\delta \geq 0$ and $x, y \in C$ with $x \leq y$.

Lemma ([Bian et al., 2017])

If F is DR-submodular, then it is up-concave.

Equivalent definitions and examples

More properties of DR-submodular functions [Bian et al., 2017]

- A differentiable function is DR-submodular if and only if

$$\nabla F(x) \geq \nabla F(y) \quad \text{for any } x, y \text{ with } x \leq y.$$

- A twice-differentiable function is DR-submodular if and only if

$$\nabla^2 F(x) = \left(\frac{\partial^2 F(x)}{\partial x_i \partial x_j} \right) \leq 0.$$

Examples

- Quadratic functions $x^\top Ax/2 + b^\top x + c$ with $A \leq 0$.
- $\sum_{i,j} \varphi_{i,j}(x_i - x_j)$ where $\varphi_{i,j}$ is convex for every i, j .
- $g(\sum_i w_i x_i)$ where g is concave and $w \geq 0$.
- $\log \det(\sum_i x_i A_i)$ where each A_i is positive definite and $x \geq 0$.

Applications of DR-submodular functions

- Isotonic regression [[Bach, 2018](#)].
- Robust budget allocation [[Soma et al., 2014](#), [Staib and Jegelka, 2017](#)].
- Online resource allocation [[Eghbali and Fazel, 2016](#)].
- Adwords for e-commerce and advertising [[Devanur and Jain, 2012](#), [Mehta et al., 2005](#)].

Continuous submodular maximization

Continuous submodular maximization

$$\begin{array}{ll} \text{maximize} & F(x) \\ \text{subject to} & x \in C \end{array}$$

where

- F is continuous **DR-submodular**,
- F is monotone, i.e. $F(x) \leq F(y)$ for any x, y with $x \leq y$,
- C is a **convex** constraint set,
- $0 \in C$,
- C is **down-closed**, i.e. $y \in C$ and $0 \leq x \leq y$ implies $x \in C$.

Conditional gradient method [Bian et al., 2017]

- Extension of the continuous greedy algorithm.
- Often called the Frank-Wolfe algorithm for submodular maximization.

Conditional gradient method

Recall

Algorithm 2 Continuous greedy algorithm [Calinescu et al., 2007, Vondrak, 2008]

Start with $x(0) = 0$.

Let $v(x) = \arg \max_{v \in P} \{\nabla F(x)^\top v\}$.

Set $dx/dt = v(x)$.

Output $x(1)$.

The conditional gradient method for SFM is given by

Algorithm 3 Conditional gradient method [Bian et al., 2017]

Start with $x_0 = 0$.

for $t = 1, \dots, T$ **do**

 Obtain $v_t \in \arg \max_{v \in C} \{\nabla F(x_{t-1})^\top v\}$.

 Update $x_t = x_{t-1} + (1/T)v_t$.

end for

Output x_T .

Conditional gradient method

Theorem ([Bian et al., 2017])

Assume that F is monotone, β -smooth in the ℓ_2 -norm, and DR-submodular. We further assume that $0 \in C$, C is down-closed, and $\|v\|_2 \leq R$ for any $v \in R$. Then x_T returned by conditional gradient (Algorithm 3) satisfies

$$F(x_T) \geq \left(1 - \frac{1}{e}\right) \max_{x \in C} F(x) - \frac{\beta R^2}{2T}$$

under $F(0) = 0$.

Conditional gradient method

Conditional gradient method

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